Precise positioning & safety IMU

ST MEMS sensors technology

ST IMU family

Precise positioning system

Video

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MEMS means Micro Electro-Mechanical System



Not only electrons are moving in motion sensors!



ST MEMS cover all the application domains



The 6 degree-of-freedom (DOF) IMU family

A diversified offer for each application, the 6x IMU expands further

More applications on the way to become safety critical

ASM330LHHX / LHHXG1

Embedded MLC⁽¹⁾ and FSM⁽²⁾

Embedded MLC and FSM

⁽¹⁾Machine Learning Core ⁽²⁾Finite State Machine

The hardware configuration the redundancy concept with ASM330LHB / LHBG1

Application hint: recommended mounting position on the PCB

Adopted approach according to ISO26262:

Software safety mechanisms realized through

the **Safety Engine** (that is a software library,

certified ASILB according to ISO26262) and

Safety element out-of-context

loaded in a host processor

Precise positioning system

End-to-end positioning solution for safe ADAS or autonomy from ST and Swift Navigation.

Includes ST ASIL-B 6-axis IMU, TeseoAPP multiband GNSS chipset & Swift Starling positioning and Skylark corrections.

High precision functional safety to enable assisted and autonomous driving

Reliable accuracy even in challenging driving conditions

Portable safety software library allows scalability to triple frequency solution

Recorded video

ASIL-B precise positioning architecture

Integrity, protection levels, TIR, and ASIL

Integrity: a measure of trust that can be placed in the correctness of the information supplied by the system.

Protection Level (PL): Maximum allowed error bound considering current conditions.

Target Integrity Risk (TIR): Probability that the actual error exceeds the PL (defined by the TIR requirements: i.e.- 10⁻⁴, 10⁻⁵, 10⁻⁶, or 10⁻⁷ per hour)

Automotive Safety Integrity Level (ASIL):

Higher TIRs require an ASIL-level analysis of the system safety case to assure meeting the TIR.

ASM330LHB & TeseoAPP performance with Starling PE

