



## Next generation in-cabin camera

### In-cabin 3D mapping for occupancy & driver monitoring







# DepthIQ pipeline overview



### **Sensor module + Image signal processor = 2D vision**



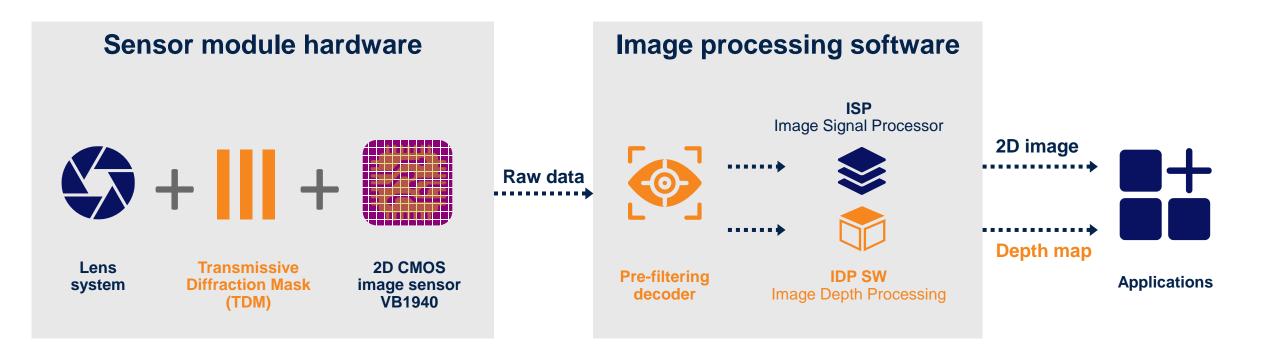








# DepthIQ pipeline overview



### TDM + CMOS sensor + Lightweight algorithm = 3D vision













### RGBIR 3D performance

#### **Cost effective**

- ✓ Low complexity no special optics required, no additional specific illumination required
- ✓ Ease of implementation just drop the 2D to 3D image sensor
- ✓ Single sensor for 2D & 3D

#### **Efficient**

- ✓ Compactness the smallest 3D camera
- ✓ Keep the 2D image sensor resolution
- ✓ Accuracy comparable to standard stereo technologies

#### Low processing complexity

 ✓ Light algorithm already ported and validated on Jetson, Snapdragon, and Rockchip







## VB1940 at a glance

### Best-in-class hybrid sensor with embedded cybersecurity features

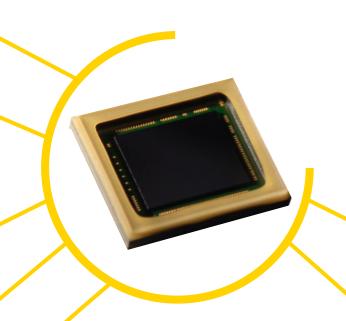
**5.1Mpx** resolution, **2.25μm** pixel size **1/2.5**" optical format

**BSI 3D stacked** sensor (65/40nm) **5.8 mm x 4.5 mm** array size

On-chip bayerization ISP
On-chip NIR smart upscale
On-chip color HDR merge

100 dB HDR in rolling shutter
Independent exposure controls (RGB and IR)

**Analog subsampling** (x2, x4, x32) **60 fps** at full resolution



**ISO26262 compliant** to support **ASIL-B** system integration

4 programmable contexts with up to 32 elements







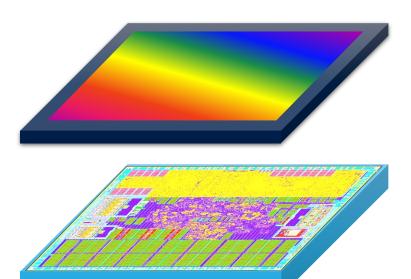
## ST's unique in-house 3D stacked BSI technology

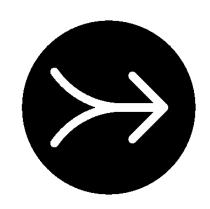
### The photo-site array

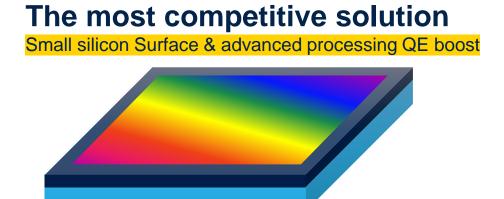
Pixel is on top level wafer only (no split over top & bottom wafer)



Die size is limited to optical area







### The low power processor

analog & digital on the whole bottom die (no need to be placed on the surroundings)



More on-chip processing without Si increase







## ST's automotive image sensors portfolio

