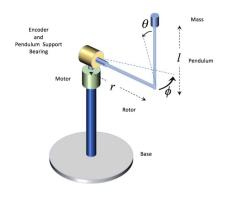




Firmware for STEVAL-EDUKIT01 evaluation kit for education on motor control and control systems





Product summary		
Firmware for STEVAL- EDUKIT01 evaluation kit for education on motor control and control systems	STSW- EDUKIT01	
Evaluation kit for education on motor control and control systems	STEVAL- EDUKIT01	
STM32 Nucleo-64 development board with STM32F401RE MCU	NUCLEO- F401RE	
Stepper motor driver expansion board based on L6474 for STM32 Nucleo	X-NUCLEO- IHM01A1	
Open source graduate level educational material and application examples	www.st.com/ motorcontrol- edu	
Applications	Factory Automation Industrial Motor Control	

Features

- Digital stepper motor control:
 - Phase current limit/control
 - Adjustable motor speed
 - Fully protected power stage
- Interfaces:
 - Bidirectional UART over USB
 - Magnetic quadrature rotary encoder interface
- Framework
 - Allows experimenting with different motor control strategies
 - Allows experimenting with advanced control algorithms

Description

The STSW-EDUKIT01 firmware allows testing of the STEVAL-EDUKIT01 rotary inverted pendulum kit and embeds the software for the X-NUCLEO-IHM01A1 stepper motor expansion board included in the kit.

The firmware allows correct configuration of the rotary encoder parameters for the stepper motor included in the STEVAL-EDUKIT01 interface via dedicated timers.

It also performs closed loop system control through the STM32 ARM-Cortex M4 microcontroller on the NUCLEO-F401RE development board.

The firmware includes a bidirectional UART interface to send operating parameters to a PC and to receive commands to change system operation and configuration.

A dedicated Matlab user interface is also provided to help you modify the motor control parameters according to specific rotor response characteristics.

The educational set, with real-time Matlab viewer and interface, helps you build your understanding of ARM-based embedded architecture (STM32CubeIDE), stepper motor control and real-time systems based on proportional, integral, derivative (PID) control, as well as more advanced techniques such as State Space or State Space with linear quadratic regulator (LQR).

A further set of open source tutorials and training material is at your complete disposal at www.st.com/motorcontrol-edu.



Revision history

Table 1. Document revision history

Date	Version	Changes
15-Apr-2020	1	Initial release.

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