

Compact reference design kit for robotics and automation



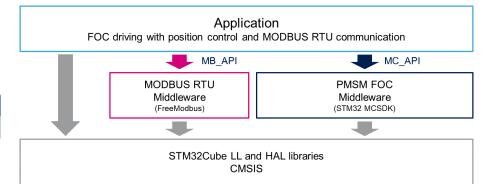
Features

- Based on MotorControl SDK 5.4.3
- Position control via encoder feedback
- MODBUS RTU communication
- Project example for the following toolchains:
 - IAR Embedded Workbench
 - KEIL-ARM μVision
 - STM32CubeIDE

Description

The STSW-ROBOT-1 is the firmware example of the EVALKIT-ROBOT-1 evaluation kit

This firmware offers positioning control based on the Field Oriented Control library and interfacing through RS485 according to the MODBUS RTU protocol.



Product status link

STSW-ROBOT-1



Revision history

Table 1. Document revision history

Date	Version	Changes
9-Mar-2020	1	Initial release.

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